

| | | | | | | | |
|-----------------|---|--|--------|--------------------|---|------------|-----------|
| R | $\begin{bmatrix} 0.996778338 & -0.013286276 & 0.079097524 \\ 0.017394967 & 0.998522297 & -0.051484338 \\ -0.07829661 & 0.052694372 & 0.995536511 \end{bmatrix}$ | | | T | $\begin{bmatrix} 2.331420007 & 0.011298935 & 0.086215339 \end{bmatrix}$ | | |
| Rotation angles | S_B | | S_A | Translation values | S_X | S_Y | S_Z |
| | 4.543° | | 2.951° | | 43.163 mm | -26.566 mm | -2.218 mm |