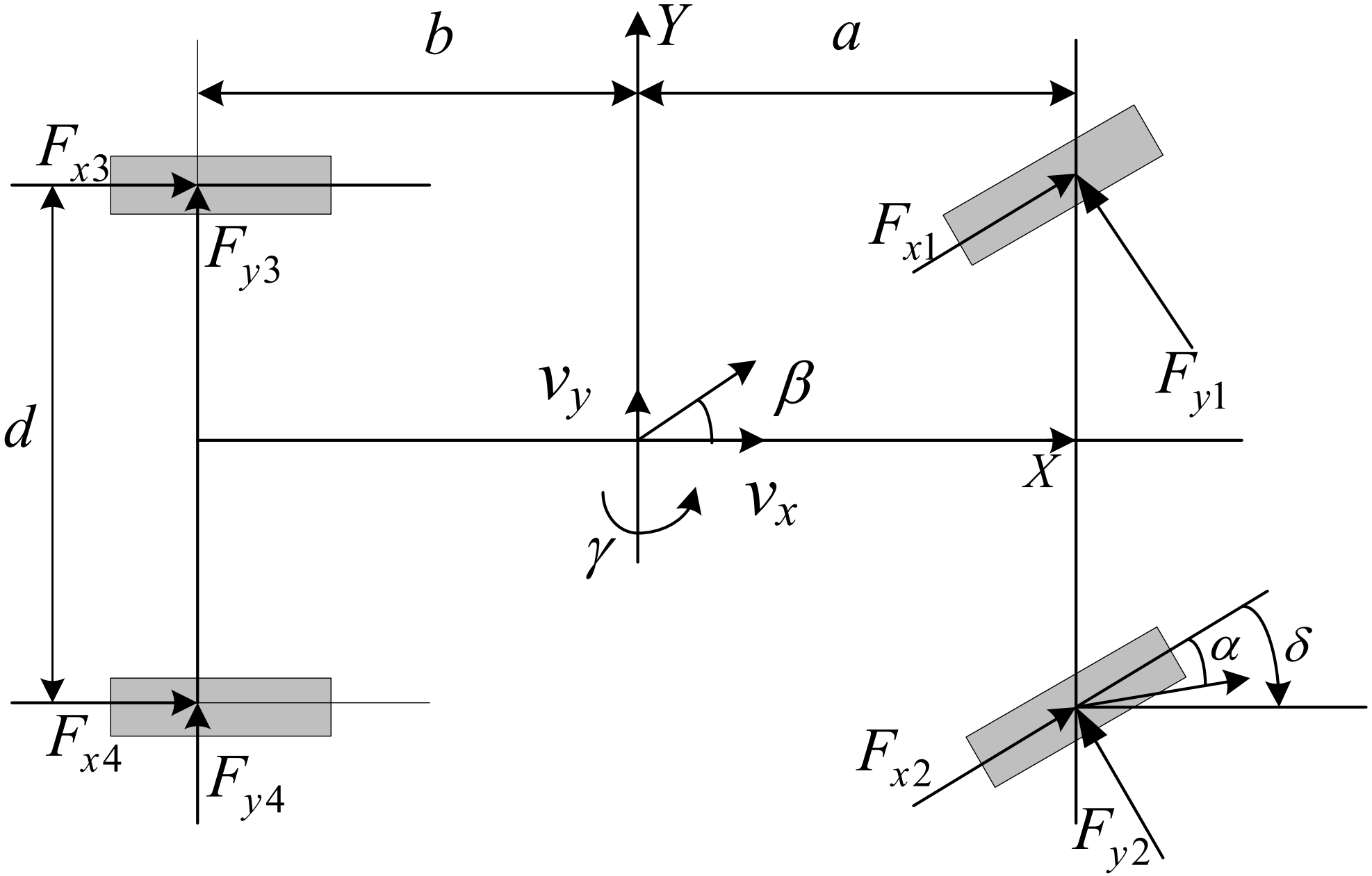
b
Y
a
F_{x3}
F_{y3}
F_{x1}
F_{y1}
d
v_y
β
X
v_x
γ
α
δ
F_{x4}
F_{y4}
F_{x2}
F_{y2}