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# Statistical analysis of energy consumption, tool wear and surface roughness in machining of Titanium alloy (Ti-6Al-4V) under dry, wet and cryogenic conditions

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Abstract. Productivity and economy are key elements of any sustainable manufacturing system. While productivity is associated to quantity and quality, economy focuses on energy efficient processes achieving an overall high output to input ratio. Machining of hard-to-cut materials has always posed a challenge due to increased tool wear and energy loss. Cryogenics have emerged as an effective means to improve sustainability in the recent past. In the present research the use of cooling conditions has been investigated as an input variable to analyze its effect on tool wear, specific cutting energy and surface roughness in combination with other input machining parameters of feed rate, cutting speed and depth of cut. Experimental design was based on Taguchi design of experiment. Analysis of Variance (ANOVA) was carried out to ascertain the contribution ratio of each input. Results showed the positive effect of coolant usage, particularly cryogenic, on process responses. Tool wear was improved by 33 % whereas specific cutting energy and surface roughness were improved by 10 % and 9 % respectively by adapting the optimum machining conditions.

#### 1 Introduction

In the present day world major efforts are made to ensure that industry processes are as productive and efficient as possible. From year 1751-2000 around  $337\times10^9$  t CO<sub>2</sub> was emitted into the atmosphere leading to global warming as well as environmental degradation (Jaffery et al., 2014). The industrial sector accounts for around 26% of the total CO<sub>2</sub> emissions (Birol, 2017). Manufacturing sectors accounts for almost 50% of these emissions. Environmental concerns as well as energy security issues have focused research towards sustainability, productivity and economy of manufacturing processes. This has led towards the objective of process optimization where output responses are augmented by careful selection of input parameters.

Machining is a major sector in the manufacturing industries capable of producing parts with precision and accuracy working with different materials like metals, non metals and polymers (Childs et al., 2000). Machining accounts for almost 10% of all manufacturing industry energy consumption (Zhao et al., 2016). In various industries turning represents a major chunk of machining processes while in the aerospace industry turning accounts for almost 85 % of the total machining time in an aircraft engine (Bermingham et al., 2012a). While pure Titanium may not fulfill requisite engineering needs being soft its alloys holds the central place in a number of industries including aerospace (Ezugwu et al., 2003), marine (Ezugwu and Wang, 1997) & medical fields (Lundgren et al., 1997). Owing to its good corrosion resistance and elevated ratio of strength to weight titanium alloys are the preferred choice for making parts like compressor blades, fasteners and exhaust shrouds in aerospace industry (Boyer, 1996). About 60 % of all titanium alloy usage consists of Ti-6Al-4V (López de lacalle et al., 2000) because of its excellent properties as shown in Table 1.

Machining of titanium alloys presents several challenges in terms of tool life and machinability. Its low thermal conductivity raises temperature of cutting face significantly reducing tool life (Donachie, 2000). The elevated temperature strength associated with titanium alloys causes deformation of the cutting tool (Ezugwu et al., 2003). Chatter and tolerance issues arise because of lower elastic modulus (Bridges and Magnus, 2001). Its chemical reactivity acts as catalyst in wear inducing mechanisms (Hong et al., 2001). Although dry cutting has greatly been favored due to environmental concerns associated with oil based coolants, use of cooling media requires due attention while in pursuit of improving overall efficiency because of the hard-to-cut status of titanium alloys

Keeping in view titanium tool wear researchers have recommended cutting velocity between 30–60 m min<sup>-1</sup> (Komanduri and Von Turkovich, 1981; Kitagawa et al., 1997) but that comes at the cost of productivity. In order to increase the speed from 60 to 120 m min<sup>-1</sup> and even beyond (industry goal is 100 m min<sup>-1</sup> and above; Bermingham et al., 2011) the employment of coolant comes in. The use of a coolant is quite well known practice ranging from traditional high pressure coolant (HPC) (Sivaiah and Chakradhar, 2018; Sun et al., 2015) to minimum quantity lubrication (MQL) (Kaynak et al., 2014; Senevirathne and Punchihewa, 2017; Khatri and Jahan, 2018) and then with the introduction of cryogenic coolants (Aramcharoen, 2016; Bagherzadeh and Budak, 2018; Bermingham et al., 2011; Bordin et al., 2015; Zhao and Hong, 1992a; Lu et al., 2018; Hong et al., 1999) i.e. Liquid Nitrogen, Argon to name a few. The cost effects of coolant needs to be weighed against advantages as coolants accounts for almost 20 % of the total manufacturing cost (Shokrani et al., 2012; Sreejith and Ngoi, 2000). This important aspect will be taken up as future work by the authors. Bermingham et al. (2011) had concluded that correct selection of machining parameters are as effective in enhancing tool life as the use of coolant. Nevertheless higher productivity and economy can be achieved by use of suitable coolant at already optimized machining parameters. Optimization can be performed by determining the best machining conditions for a particular response. Researchers have optimized different machining responses of various work piece materials taking into consideration diverse input parameters (Debnath et al., 2016; Asiltürk and Neşeli, 2012; Mia and Dhar, 2017; Younas et al., 2019). Prasanna et al. (2014) considered feed, speed and air pressure during dry drilling of Ti-6Al-4V to optimize overcut, taper circularity and cutting forces. Researchers found that thrust force mainly depends on spindle speed along with feed rate whereas drilling dimensional accuracy is influenced by spindle speed and air pressure. Surface integrity and temperature were optimized by Escamilla-Salazar et al. (2013) in milling of Ti alloy by applying the particle swarm technique. It was shown that machining optimization can be achieved using swarm technique with substantial validity. Hashmi et al. (2016) optimized surface roughness during Ti-6Al-4V milling. Research showed surface integrity is mainly reliant on depth of cut. Surface integrity and tool life were optimized by Hasçalık and Çaydaş (2008) turning Ti-6Al-4V. Results found tool life highly dependent on cutting depth. Surface roughness was mainly affected by cutting speed. Zain et al. (2010) optimized surface roughness using simulated annealing in end milling. Feed, speed and rake angle were the input parameters. It was concluded that highest speed and rake angle resulted in lowest surface roughness at lowest feed values. Sarıkaya and Güllü (2015) selected cutting speed and cutting fluid flow rate to minimize surface roughness and tool wear during turning of Haynes 25 alloy. Process optimization was reached at cutting speed of  $30 \,\mathrm{m \, min^{-1}}$  and flow rate of  $180 \,\mathrm{mL \, h^{-1}}$ . Earlier researchers carried out turning of Ti-6Al-4V to optimize different responses (Mia et al., 2017). Cooling condition (dry and HPC) was selected as an input parameter in addition to feed and cutting speed. Mono objective optimization showed that surface roughness and cutting forces were optimized at 0.12 mm rev<sup>-1</sup> feed and 156 m min<sup>-1</sup> speed under wet cutting. On the other hand cutting temperature and friction coefficient were optimized at 0.12 mm rev<sup>-1</sup> feed and 78 m min<sup>-1</sup> speed under dry conditions. Another study of the same authors incorporated cryogenic cutting along with dry cutting in turning of Ti-6Al-4V (Mia et al., 2019). Feed and speed were taken as other input parameters. Different configurations of cryogenic cutting were analyzed. It was found that dual jet configurations operating at cutting speed of 140 m min<sup>-1</sup> and feed of 0.16 mm rev<sup>-1</sup> optimized the collective output of tool wear, surface roughness and specific cutting energy. The motivation of present study was to combine dry, wet and cryogenic conditions as a single input variable for comparison. In addition depth of cut was also incorporated to study its effect on output responses. Novelty was based on the fact that cooling/lubrication conditions and depth of cut vested as input variables further improve the sustainability and efficiency of the manufacturing system. This research is based on the concept that productivity is the cross product of quality, utilization and efficiency (Laperrire and Reinhart, 2014). These words encompass the manufacturing process taking into account vital signs like energy, wear and output quality. These responses are optimized using constructive combinations of input parameters including feed, speed and depth of cut. Taguchi design of experiment is adopted to collectively optimize the input parameters which otherwise behave differently for different responses. The aim is to formulate and optimize responses in terms of input parameters which are sustainable and productive at the same time.

Property	Material					
	Titanium	Ti-6Al-4V	Ti-6Al-6V-2Sn	Ti-10V-2Fe-3Al	Inconel 718	Al 7075-T6 Alloy
Density (g cm <sup>-3</sup> )	4.5	4.43	4.54	4.65	8.22	2.81
Hardness (HRC)	10-12 (equivalent)	30-36	38	32	38-44	$\sim$ 7 (equivalent)
Ultimate Tensile Strength (MPa)	220	950	1050	970	1350	572
Yield strength (MPa)	140	880	980	900	1170	503
Modulus of elasticity (GPa)	116	113.8	110	110	200	71.7
Ductility (%)	54	14	14	9	16	11
Fracture toughness (MPa m <sup>1/2</sup> )	70	75	60	_	96.4	20-29
Thermal Conductivity ( $W m K^{-1}$ )	17	6.7	6.6	7.8	11.4	130

315

315

 $\sim 150$ 

Table 1. Comparison of aerospace alloys properties (Jaffery et al., 2015).

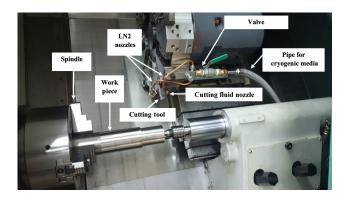


Figure 1. Experimental setup with add-on cryogenic apparatus.

Table 2. Chemical Composition (wt %) of Ti-6Al-4V.

Max. operating temperature (°C)

Ti	V	Al	Fe	Cu	Cr
89.44	4.2	5.7	0.15	0.003	0.0023

#### 2 Experimental details

## 2.1 Experimental setup

Computerized numerical control (CNC) turning center ML-300 (Rated power 26 KW and maximum spindle speed 3500 RPM) as shown in Fig. 1 was used for turning operation of Ti-6Al-4V bar. Table 2 displays the chemical composition of work piece. Straight carbide cutting inserts supplied by SANDVIK CCMW 09 T3 04 H13 (uncoated with 0° rake angle) were used. Carbide tool is recommended for machining titanium based alloys because of its impact strength and toughness over varying temperature ranges (Zhao and Hong, 1992b). Each experimental run was carried out with a new insert for inspection and record. Power calculations were done using clamp on Yokogawa Power Analyzer CW-240-F meter. Roughness tester TR 110 meter was used to determine surface roughness. It had a measuring range of 0.05–10.0 µm.

Dry, wet and cryogenic conditions were used during experimentation on equipment shown in Fig. 2. Internal cool-



315

650

Figure 2. CNC Turning centre with cryogenic setup and response measuring equipment.

ing system of CNC Turning center ML-300 was used for wet conditions. It has a coolant pump of 0.8 kW rating which uses water based coolant oil shell dromus B. A steady flow rate of 6 L min<sup>-1</sup> was maintained during wet cutting. High pressure cylinder XL-160 was used in the cryogenic setup. It can store 160 L of cryogenic media. Liquid nitrogen was selected as cryogenic media because of its effectiveness with titanium work material and carbide tool combination (Hong, 2006). Due to its worldwide availability and inert nature LN2 is the most widely used cryogenic media (Jawahir et al., 2016). Pressure of 20 psi was maintained using a pressure regulator developing a flow rate of 4 L min<sup>-1</sup>. Vacuum insulated pipes were used to carry the media to two copper pipes with 4 mm dia through a bifurcated cryogenic needle valve. Previous researches (Bermingham et al., 2012b; Hong and Ding, 2001; Mia et al., 2019) have found that using dual jets one each at flank and rake face produced optimum results.

#### 2.2 Response measurement

Measured responses included specific cutting energy (SCE), tool wear rate (R), surface roughness (Ra) and material removal rate (MRR). Multiple readings were taken which were averaged for accuracy. ISO 3685 was followed for tool wear



Figure 3. Optical microscopy image showing maximum flank wear.

verdict which says that criteria of flank wear (VB) is either average 0.3 or maximum 0.6 mm. Optical microscopy was used for wear measurement as shown in Fig. 3.

Since accuracy and product quality are highly influenced by flank wear it is mostly considered in industrial machining (Jaffery and Mativenga, 2008). Moreover flank wear is related to substrate properties, whereas crater wear reflects coating properties (Fitzsimmons and Sarin, 2001). *R* was calculated using Eq. (1). A lower tool wear will be symbolized by a higher negative value of *R* (Jaffery and Mativenga, 2009, 2008).

$$R = \log \left\lceil \frac{\text{VB}}{l_s} \right\rceil = \left\lceil \frac{\text{VB}}{1000t V_c} \right\rceil \tag{1}$$

where  $l_s$  is spiral length and t is the cutting time. SCE (amount of energy required to remove unit volume of material) was calculated using Eq. (2). It must be noted that efficiency or type of CNC machine has no effect on SCE.

SCE 
$$(J \,\text{mm}^{-3}) = \frac{P_{\text{cut}}(W)}{\text{MRR}(\text{mm}^3 \,\text{s}^{-1})}$$
 (2)

 $P_{\rm cut}$  (W) was calculated employing a two cycle approach making use of Eq. (3). The two cycle approach refers to practice of measuring power twice for the same input parameters i.e.  $P_{\rm actual}$  and  $P_{\rm air}$  where  $P_{\rm actual}$  is the actual cutting power whereas  $P_{\rm air}$  is power consumed during an offset air cut. Their difference gives  $P_{\rm cut}$  which is the actual power utilized in cutting operation.  $P_{\rm cut}$  is therefore independent of machine/tool type and rating. MRR i.e. the amount of volume removed per unit time was determined using Eq. (4).

$$P_{\text{cut}}(W) = P_{\text{actual}}(W) - P_{\text{air}}(W)$$
(3)

$$MRR = f \times v \times d \tag{4}$$

Equation (3) is an effective method for measurement of power utilized during cutting operation (Li and Kara, 2011;

Table 3. Selected input machining parameters.

Parameters	$\begin{array}{c} \text{Feed} \\ \text{rate} \\ (\text{mm rev}^{-1}) \end{array}$	Cutting speed $(m \min^{-1})$		Cooling/ lubrication conditions
Level 1	0.12	50	1	Dry
Level 2	0.16	100	1.5	Wet
Level 3	0.20	150	2	Cryogenic

Table 4. Taguchi Orthogonal Array (L9) of cutting parameters.

Run	Feed rate (mm rev <sup>-1</sup> )	Cutting speed (m min <sup>-1</sup> )	Depth of cut (mm)	Cooling/ lubrication conditions*
1	0.12	50	1	1
2	0.12	100	1.5	2
3	0.12	150	2	3
4	0.16	50	1.5	3
5	0.16	100	2	1
6	0.16	150	1	2
7	0.20	50	2	2
8	0.20	100	1	3
9	0.20	150	1.5	1

<sup>\*</sup> 1 = dry, 2 = wet and <math>3 = cryogenic.

Warsi et al., 2018, 2017). It must be noted that while calculating the  $P_{\text{air}}$  and  $P_{\text{actual}}$  utmost care was taken to avoid unnecessary or exaggerated points corresponding to rapid tool travel just before/after cut finished.

# 2.3 Design of experiment

Feed rate, cutting speed, depth of cut and cooling/lubrication conditions were taken as input variables. It can be concluded from literature (Behera et al., 2017; Warsi et al., 2018) that these variables have significant effect on machining output response. Table 3 shows selected levels of input parameters keeping in view tool manufacturer guidelines (Sandvik, 2015) and ISO standard (1993).

Taguchi design of experiment was preferred over full factorial because of its overall efficiency in term of lesser runs (Ross and Ross, 1988). Table 4 displays the formulated Taguchi design orthogonal array.

#### 3 Results and discussion

The experimental results of measured responses are tabulated in Table 5. Each response was measured twice by repetition of experimental run.

Best and worst values of any response can be seen albeit within the avail combination of cutting parameters and in isolation with each other. To draw useful information from ex-

Table 5. Measured responses during experimentation.

Run	Wear r	ate (R)	Ra (	μm)	SCE (J mm <sup>-3</sup> )	
	Trial A	Trial B	Trial A	Trial B	Trial A	Trial B
1	-6.1684	-6.2044	1.51	1.53	1.1004	1.1504
2	-6.1408	-6.1797	1.19	1.21	1.2338	1.3005
3	-5.9364	-5.9564	1.13	1.15	1.2005	1.2338
4	-6.1815	-6.2215	1.82	1.84	1.0004	1.0754
5	-5.7789	-5.7845	1.75	1.77	1.1630	1.2192
6	-5.7489	-5.7877	1.61	1.63	1.3005	1.3756
7	-5.9325	-5.9525	2.96	2.98	1.0804	1.1104
8	-5.8682	-5.8924	2.61	2.63	1.1104	1.1705
9	-5.1689	-5.1959	2.66	2.68	1.2405	1.2805

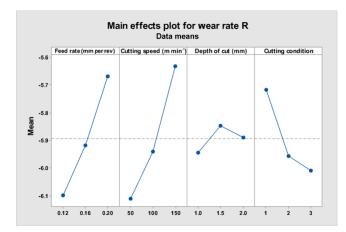


Figure 4. Main effects plot for R.

perimental results each response was individually plotted and analyzed.

#### 3.1 Effects on tool wear

Flank wear (VB) of each run was measured using optical microscopy. Tool wear rate was calculated from Eq. (1). Main effects plot of R is shown in Fig. 4. It shows that wear rate increases with increasing feed and speed. Cutting depth displays an inconsistent response by initially increasing and then decreasing. In terms of coolant usage cryogenic condition has significantly reduced R as shown in the Fig. 4.

The increase of wear rate with increasing feed can be attributed to lower rate of heat dissipation (Sarwar et al., 2009). Enhanced vibration at tool-work piece interface at higher feed values also contributes towards higher wear (Yan and Li, 2013). Titanium by virtue of its lower thermal conductivity gets heated up particularly at high cutting speed reaching in excess of 800 °C (Ezugwu and Wang, 1997) as temperature of cutting zone is directly proportional to cutting speed (Fan et al., 2016; Shaw, 2005). Figure 5 displays the relationship between cutting speed and temperature. Since all wear mechanisms are directly proportional to heat the tool wears out at an aggravated rate when machined at elevated speed

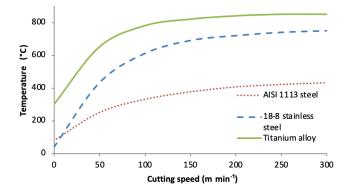


Figure 5. Relationship between cutting speed and temperature for different materials (data from Shaw, 2005).

values especially under dry conditions. Diffusion dissolution and abrasion wear mechanisms, which are the primary causes (Bermingham et al., 2012b) of tool failure increases manifolds with increasing heat in cutting zone. This is the reason why the worst tool wear is expected to be in dry conditions at max feed and speed as shown by earlier researchers (Ahsan et al., 2012; Kumar and Choudhury, 2008; Venugopal et al., 2007; Bermingham et al., 2011; Sun et al., 2010a).

The liquid nitrogen media provides a temperature of  $-196\,^{\circ}\text{C}$  in the cutting zone (Bermingham et al., 2011). Generally coolants are more efficient at lower values of speed and feed (Venugopal et al., 2007). The reason for this observation is that the coolant can penetrate cutting zone easily at lower speed and feed. Also Bermingham et al. (2011) found that cryogenic media enhances tool life by mainly preventing the production and hence transfer of heat to tool and to a lesser extent by extricating the heat produced. This is because cryogenic media reduces contact length between tool-chip and resultantly reduces the frictional heat generated. ANOVA was performed to determine the influence of each factor on tool wear as shown in Table 6.

Values of S and R-Sq (pred) indicates that experimental data can be used to predict other value points with validity. The P value indicates that all factors are substantially contributing the response. The main contributing factor for R comes out to be speed (44.39%) closely followed by feed (35.15%).

# 3.2 Effects on specific cutting energy

Specific cutting energy (J mm $^{-3}$ ) is plotted against the input parameters as shown in Fig. 6. SCE is decreasing with increasing feed and decreasing speed as shown in Fig. 6. As for speed Warsi et al. (2018) showed an opposite behavior i.e. decreasing SCE with increasing speed as shown in Fig. 7. The SCE denoted with a dotted line shows a decrease as the speed is increased with an increasing trend around  $1000\,\mathrm{m\,s^{-1}}$ . An argument can arise that present research is at cutting speed of 50 to  $150\,\mathrm{m\,min^{-1}}$  as opposed to  $250\,\mathrm{to}$ 

**Table 6.** ANOVA for Wear rate *R*.

Source	DF	Seq SS	Adj SS	Adj MS	F Value	P Value	CR
$f \text{ (mm rev}^{-1})$	2	0.55751	0.557511	0.278755	622.48	0.000	35.15 %
$v  (\mathrm{m  min^{-1}})$	2	0.70410	0.704104	0.352052	786.16	0.000	44.39 %
d (mm)	2	0.02836	0.028358	0.014179	31.66	0.000	1.79 %
CC	2	0.29205	0.292055	0.146027	326.09	0.000	18.41 %
Error	9	0.00403	0.004030	0.000448			0.25 %
Total	17	1.58606					100.00 %
SD = 0.0211616, R-Sq = 99.75 %, R-Sq(pred) = 98.98 %							

DF – degrees of freedom, SS – sum of squares, MS – mean squares, F - F value, P - P value, CR – contribution ratio (%), SD – standard deviation, R-Sq.(pred) – predicted  $R^2$ .

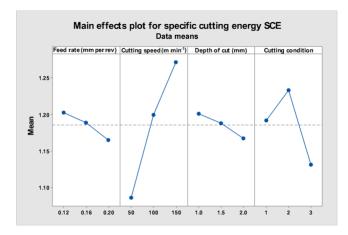


Figure 6. Main effects plot for SCE.

1500 m min<sup>-1</sup> speed considered by Warsi et al. (2018). To confirm the independence of this fact, turning of Al was also carried out at same speed. The result showed that Al even at the present research speed displayed a decrease in SCE with increasing speed.

Another important point is the cutting speed categories which were considered in both the cases as chalked out by Schulz and Moriwaki (1992) as shown in Fig. 8. It was found that both the cutting speeds were in transitional range in their respective domains, i.e.  $50 \text{ to } 150 \, \text{m s}^{-1}$  in case of titanium and 250 to  $1500 \, \text{m s}^{-1}$  in case of aluminum. It can be said that both titanium and aluminum showed comparatively same trend in same category (transition). The findings are aligned with results of Pervaiz et al. (2013) which concluded that cutting forces increases by increasing speed above  $60 \, \text{m min}^{-1}$  during turning of Ti-6Al-4V.

During turning a number of forces acts in certain directions as described in merchants circle (Shaw, 2005). These forces which plays a vital role in SCE and for that matter in tool wear usually decreases with increasing temperature (Kalyan and Samuel, 2015). Nevertheless, it is also reported (Schulz et al., 1981; Komanduri et al., 1984) that the cutting forces increase again after reaching a minimum value. More-

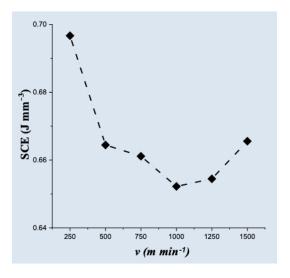


Figure 7. SCE relationship with cutting speed (data from Warsi et al., 2018).

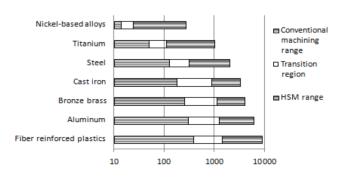


Figure 8. Cutting speed ranges for machining of different materials (data from Schulz and Moriwaki, 1992).

over with the introduction of cryogenic cooling new dimensions are added as suggested by Bermingham et al. (2011). It is concluded that SCE is a material based property and it depends on a number of external and inherent factors e.g. thermal softening occurring at higher temperatures (Sun et al., 2010b) in opposition to high temperature strength (Ezugwu

Table 7. ANOVA for SCE.

Source	DF	Seq SS	Adj SS	Adj MS	F Value	P Value	CR
$f  (\text{mm rev}^{-1})$	2	0.004370	0.004370	0.002185	1.38	0.301	2.76 %
$v  (\mathrm{m  min}^{-1})$	2	0.105097	0.105097	0.052549	33.08	0.000	66.28%
d (mm)	2	0.003412	0.003412	0.001706	1.07	0.382	2.15 %
CC	2	0.031401	0.031401	0.015701	9.88	0.005	19.80%
Error	9	0.014297	0.014297	0.001589			9.02%
Total	17	0.158577					100 %
SD = 0.0262233, R-Sq = 97.44 %, R-Sq(pred) = 93.94 %							

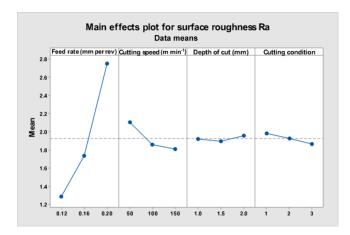


Figure 9. Main effects plot for Ra.

et al., 2003) associated with titanium alloys. Reasons for increasing SCE with speed can be ascribed to work hardening of titanium alloy during machining and aggravated tool wear at higher cutting speeds (Jaffery and Mativenga, 2008; Younas et al., 2019).

In case of cryogenic cooling, work hardening is the major contributor towards SCE as compared to thermal softening. As work hardening is known to decrease with decreasing temperature (Chichili et al., 1998), cryogenic machining (–196 °C) shows lower SCE in comparison with dry and wet machining. However, in case of wet and dry conditions, thermal softening plays a vital role in the SCE. With increasing temperature material softens and SCE reduces. In dry machining thermal softening effect is more pronounced as compared to wet condition thus resulting in lower SCE (Pervaiz et al., 2013).

ANOVA was performed to determine the influence of each factor on SCE. Table 7 displays the ANOVA for SCE. Analysis reveals that cutting speed with 66.28 % is the most significant factor followed by cooling/lubrication conditions with 19.80 %. Feed and depth of cut are insignificant members.

#### 3.3 Effects on surface roughness

Surface roughness is related to the overall product quality and hence measured as a vital output response. It increases with increasing feed and decreasing speed as shown in Fig. 9. Depth of cut showed inconsistent effect on Ra. The geometric contribution of feed rate is evident by its effect on Ra. High feed imparts microgroove over the surface which stretches and adds to Ra whereas low cutting speed creates BUE which induces chatter and worsens the roughness (Mia and Dhar, 2017). In another related study (Mia and Dhar, 2016) higher Ra was attributed to higher peaks and crest over the machined surface at greater feed values. In addition increased vibration at high feed rates also contribute towards higher Ra (Yan and Li, 2013).

Cryogenic conditions produced lowest Ra followed by wet conditions. Dry condition produced highest Ra. Better Ra with coolant is because coolant also serves as a lubricant between sliding surfaces (Dhar and Kamruzzaman, 2007). Another fact is the substantial alteration of coefficient of friction at the tool-work interface in the presence of a coolant (Strano et al., 2013). The aggravated tool wear under dry (no-coolant/lubricant) condition also increases the Ra and counteracts against the thermal softening gain. Comparable findings are reported by earlier researchers (Bordin et al., 2015; Mia, 2017). The phenomena of penetration of coolant has been reported by different authors (Mia and Dhar, 2016; Bagherzadeh and Buda, 2018; Yuan et al., 2011). The lubricating phenomena both by cryogenic and wet cutting is effective at lower cutting speed values because of the comparative ease of penetration as compared with high speed conditions (Venugopal et al., 2007). Same is evident from Fig. 9 where Ra changes drastically in the second half of speed (100 to  $150 \,\mathrm{m\,min^{-1}}$ ) and feed (0.16 to 0.20 mm) as compared to the first half. Analysis of contribution of factors is tabulated in Table 8.

The P value indicates that all factors are contributing towards response. Feed is the most influential parameters with 94.98 % contribution ratio followed by speed with 4.24 %.

Source	DF	Seq SS	Adj SS	Adj MS	F Value	P Value	CR
$f \text{ (mm rev}^{-1})$	2	6.77444	6.77444	3.38722	16936.11	0.000	94.98 %
$v  (\mathrm{m  min^{-1}})$	2	0.30271	0.30271	0.15136	756.78	0.000	4.24 %
d (mm)	2	0.00991	0.00991	0.00496	24.78	0.000	0.14%
CC	2	0.04338	0.04338	0.02169	108.44	0.000	0.61 %
Error	9	0.00180	0.00180	0.00020			0.03 %
Total	17	7.13224					100%

Table 8. ANOVA for Surface roughness Ra.

SD = 0.0141421, R-Sq = 99.95%, R-Sq(pred) = 99.90%

### 4 Validation experimentation

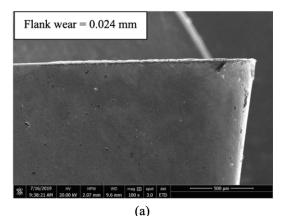
The focus of this research is the investigation of machining response taking into consideration the Cooling/lubrication conditions as the input variable along with other fundamental machining inputs. This methodology first necessitated the identification of contribution of vital input parameters and then selection of specific values which will contribute towards suitable results. In this study R, SCE and Ra were selected, based on the smaller is better model. Table 9 displays the desired values of input parameters as predicted by Taguchi methodology.

Subsequently confirmatory tests were conducted at the best and worst machining parameters combinations to validate the experimental results. Table 10 shows the results of confirmatory test in comparison with the best results obtained through Taguchi Analysis. As evident from Table 10 validation test conformed to the trends predicted using statistical analysis and Taguchi Design of Experiments. Figure 10 shows the scanning electron microscopy images of lowest and highest wear rate conditions.

#### 5 Conclusion

In the present research dry, wet and cryogenic turning of Ti-6Al-4V was carried out. Focus of attention was sustainability, productivity and economy of machining process. Selected output responses included specific cutting energy, tool wear, surface roughness and material removal rate where the first two highlights sustainability and efficiency while last two represents productivity. Following conclusions can be formulated on the basis of achieved results:

Tool Wear rate was significantly reduced by use of cryogenic and wet media. Cryogenic coolant produced the least wear result in run 4 even at elevated feed and speed conditions. This wear is 4% better than the one at lowest feed and speed under dry condition. The tool life was further improved by 33% when cryogenic machining was carried out at optimum machining parameters.



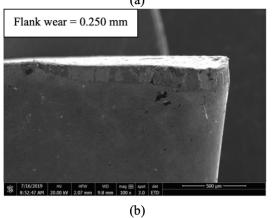


Figure 10. Scanning electron microscopy images. (a) Min wear at f = 0.12, v = 50, d = 1, cryogenic. (b) Max wear at f = 0.2, v = 150, d = 1.5, dry.

- Cutting speed had the highest contribution (44.39 %) towards tool wear followed by feed rate (35.15 %) and coolant media (18.41 %).
- Specific cutting energy in case of cryogenic machining was less as compared with dry and wet machining.
   About 10% improvement in energy consumption was achieved by use of optimum machining parameters under cryogenic conditions. Specific cutting energy of Ti-

Table 9. Machining condition sets for individual best and worst responses.

Responses	Cutting parameters				
		$f  (\text{mm rev}^{-1})$	$v  (\mathrm{m}  \mathrm{min}^{-1})$	d (mm)	CC
Wear rate, R	Best	0.12	50	1	3
	Worst	0.20	150	1.5	1
SCE (J mm <sup>-3</sup> )	Best	0.20	50	2	3
	Worst	0.12	150	1	2
Ra (µm)	Best	0.12	150	1.5	3
	Worst	0.20	50	2	1

Table 10. Comparison of validation test results with initial runs.

Response	Condition	Validation tests	Initial runs	% age difference
Wear rate R	Best	-6.3982	-6.2215	33 %
	Worst	-5.1689	-5.1689	0 %
SCE (J mm <sup>-3</sup> )	Best	0.9390	1.0004	10 %
	Worst	1.4024	1.3756	2 %
Ra (μm)	Best	0.98	1.13	9 %
	Worst	3.06	2.98	2 %

6Al-4V increases with increasing speed because of its aggravated tool wear and work hardening.

- Cutting speed had significantly higher contribution towards specific cutting energy with 66.28 % contribution ratio followed by coolant media (19.80 %). Feed rate and depth of cut had little effects with 2.76 % and 2.15 % contribution respectively.
- Higher values of speed gave better surface roughness results in contrast with higher feeds values. Use of coolant improved surface roughness because of its lubrication effect. Surface roughness was improved by 9% when machining was carried out under cryogenic conditions under optimum machining parameters.
- Surface roughness was highly influenced (94.98 % contribution ratio) by feed rate. Contribution ratio of cutting speed was 4.24 % whereas cooling condition and depth of cut were having contribution of less than 1 %.

Data availability. No data sets were used in this article.

# **Appendix A: Abbreviations**

ANOVA	Analysis of Variance
CC	Cooling/lubrication Condition
d	Depth of cut (mm)
D	Work piece diameter (mm)
f	Feed rate $(mm  rev^{-1})$
ĺ	Linear length of cut (mm)
$l_{\mathrm{s}}$	Spiral length of cut (mm)
MRR	Material removal rate (cm <sup>3</sup> s <sup>-1</sup> )
$P_{\text{actual}}$ (W)	Total power consumed during actual cutting
$P_{\rm air}\left(\mathbf{W}\right)$	Total power consumed during air cut
$P_{\rm cut}$ (W)	Power consumed for cutting operation
R	Wear rate
Ra	Surface roughness (µm)
SCE	Specific cutting energy
t	Cutting time (s)
v	Cutting speed $(m \min^{-1})$
VB	Flank wear (mm)

Author contributions. MAK and MK designed experiments. MY and SSW assisted in developing methodology and plotting graphs. SHIJ supervised MAK during experimentation and tool characterization. SIB and RA reviewed drafted paper and addressed revisions.

**Competing interests.** The authors declare that they have no conflict of interest.

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